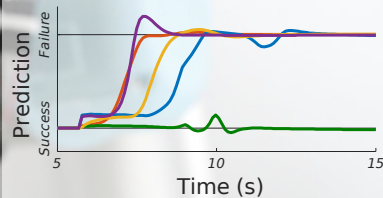


Learning

Soft sensing

Error Prediction



Passive grasping interactions

Recovery

